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# New Numerical Code for Black Hole Initial Data

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# New Numerical Code for Black Hole Initial Data

## HyperSolid

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20th Eastern Gravity Meeting  
*Penn State, University Park, PA*

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# Outline

## ① Introduction

- Problems
- Approaches
- HyperSOLID

## ② Formulation

- Equations
- Variables
- Calculations
- Separation
- Transformation
- Projection

## ③ Implementation

- Algorithm
- Numerics
- Testing

## ④ Timeline

# Problems

## *Main Problems*

- There are no exact solutions of Einstein Equations that describes a bound system radiating gravitational waves.
- One needs to resort to numerical simulations, or analytical approximation methods.
- Current methods to constrained initial data exhibit *junk radiation* and *ambiguities* about constrained and free data.

## *Possible Solutions*

- It was mathematically proved that given the correct initial data, Einstein equation will yield the expected solution.
- New formulations to calculate the constrains ensuring that the numerical system is well-behaved (hyperbolic equations).

# Approaches

## *Standard Approach*

The constraints are formulated as elliptic equations (ex: the conformal thin sandwich method, the gluing technique, etc.)

$$D_j K^j_i - D_i K^j_j = 0, \quad {}^{(3)}R + (K^j_j)^2 - K_{ij} K^{ij} = 0,$$

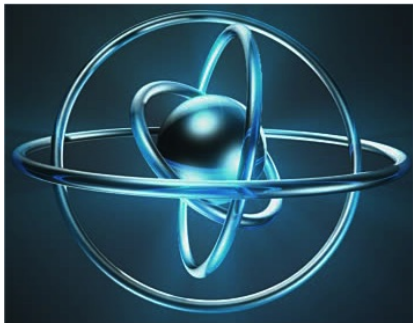
## *New Approach*

The 3D initial surfaces are further foliated into 2D surfaces, where the constraints form an algebraic-hyperbolic system:

$$\mathcal{L}_{\hat{n}} \mathbf{K} - \hat{D}^l \mathbf{k}_l + F_{\mathbf{K}} = 0, \quad \mathcal{L}_{\hat{n}} \mathbf{k}_i + \mathbf{K}^{-1} (\kappa \hat{D}_i \mathbf{K} - 2 \mathbf{k}^l \hat{D}_i \mathbf{k}_l) + F_{\mathbf{k}_i} = 0$$
$$\kappa = (2\mathbf{K})^{-1} \left( 2 \mathbf{k}^l \mathbf{k}_l - \frac{1}{2} \mathbf{K}^2 - \kappa_0 \right)$$

# HyperSolID

## Hyperbolic Solver for Initial Data



### Description

- ① General 4D metric is given on the initial time slice
- ② Free 3D initial data is constructed from the metric
- ③ Constrained 2D initial data given on the initial sphere

The constrained data is updated by solving the hyperbolic-algebraic system.

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# Equations

## Evolution Equations

$$\begin{aligned}\partial_\rho U &= \frac{1}{2} \widetilde{N} \overline{\partial} U + \frac{1}{2} \widetilde{N} \overline{\partial} U \\ &+ \frac{1}{2} \widehat{N} d^{-1} [a(\overline{\partial} \bar{v} + \overline{\partial} v) - b \overline{\partial} \bar{v} - \bar{b} \overline{\partial} v] - F_U \\ \partial_\rho v &= \frac{1}{2} \widetilde{N} \overline{\partial} v + \frac{1}{2} \widetilde{N} \overline{\partial} v - \widehat{N} U^{-1} \\ &- \widehat{N} U^{-1} \{ w \overline{\partial} U - d^{-1} [(a v - b \bar{v}) \overline{\partial} \bar{v} + (a \bar{v} - \bar{b} v) \overline{\partial} v] \} - f_v\end{aligned}$$

## Algebraic Equation

$$w = (2U)^{-1} [d^{-1}(2av\bar{v} - b\bar{v}^2 - \bar{b}v^2) - \frac{1}{2}U^2 - \kappa_0]$$



# Variables

## *Known Variables*

The known terms that enter in these formulas are:

$$\begin{aligned} & \hat{N}, (\tilde{N}, \bar{N}), (\partial\hat{N}, \bar{\partial}\hat{N}), (\partial\tilde{N}, \bar{\partial}\tilde{N}, \partial\bar{N}, \bar{\partial}\bar{N}), \\ & a, (b, \bar{b}), d, (\partial a, \bar{\partial}a), (\partial b, \bar{\partial}b, \partial\bar{b}, \bar{\partial}\bar{b}), (A, \bar{A}), (B, \bar{B}), (C, \bar{C}) \\ & \kappa_0, \hat{K}, \overset{\blacklozenge}{K}, (\overset{\blacklozenge}{K}, \bar{\overset{\blacklozenge}{K}}), (\overset{\blacklozenge}{K}, \bar{\overset{\blacklozenge}{K}}), \overset{\bullet}{K}, \partial\kappa_0, (\partial\overset{\bullet}{K}, \bar{\partial}\overset{\bullet}{K})(\partial\overset{\bullet}{K}, \bar{\partial}\overset{\bullet}{K}). \end{aligned}$$

## *Unknown Variables*

The unknown variables are:  $(U, v, w)$  and their derivatives:

$$(\partial U, \bar{\partial}U), (\partial v, \bar{\partial}v, \partial\bar{v}, \bar{\partial}\bar{v})$$

The angular derivatives are the Newman-Penrose  $(\partial, \bar{\partial})$  operators

## Calculations

### *Start-up data*

We start with a general 4D metric,  $(g_{ij}, \partial_t g_{ij})$ , in Cartesian coordinates  $(x, y, z)$ . With this data we calculate:

$$g^{ij}, n^i, h_{ij}, h^{ij} = g^{ij} + n^i n^j, (\partial_k h_{ij}, \partial_k h^{ij}, \partial_m \partial_k h_{ij})$$

$${}^3\Gamma_{jk}^i, {}^3R_{jlk}^i, {}^3R_{jk}, {}^3R, K_{ij}, K_i^j$$

### *Radial Foliation*

We choose a simple spherical foliation  $\rho = r$ , where  $r = \sqrt{\delta^{ij} x_i x_j}$ . For this foliation we calculate the quantities :

$$\hat{N} = (h^{ij} \partial_i \rho \partial_j \rho)^{-1/2}, \hat{N}^i, \hat{n}^i, \gamma_{ij} = h_{ij} - \hat{n}_i \hat{n}_j, \partial_k \gamma_{ij}, \partial_\rho \gamma_{ij}, \hat{\Gamma}_{jk}^i, \hat{K}_{ij}, \hat{K}.$$

## Separation

### *Extrinsic Curvature*

The extrinsic curvature is decomposed in:

$$K_{ij} = \kappa \hat{n}_i \hat{n}_j + 2\hat{n}_{(i} \mathbf{k}_{j)} + \mathbf{K}_{ij}, \text{ where } \mathbf{K}_{ij} = \gamma_i^k \gamma_j^l K_{kl}$$

### *Constrained Data*

$$\kappa = \hat{n}^i \hat{n}^j K_{ij}, \mathbf{k}_i = \gamma_i^j \hat{n}^k K_{jk}, \mathbf{K} = \gamma^{ij} \mathbf{K}_{ij}$$

### *Free Data*

$$\dot{\mathbf{K}}_{ij} = \mathbf{K}_{ij} - \frac{1}{2} \gamma_{ij} \mathbf{K}, \kappa_0 = {}^3R - \dot{\mathbf{K}}_{kl} \dot{\mathbf{K}}^{kl}.$$

## Transformation

### *Change of Coordinates*

From Cartesian  $(x, y, z)$  to stereographic coordinates  $(r, q, p)$

$$x = \Omega r q, y = \pm \Omega r p, z = \mp \frac{1}{2} \Omega r (-1 + q^2 + p^2), \quad \Omega = (1 + q^2 + p^2)^{-1}.$$

The coordinates of the unit sphere metric  $q_{ab} = \Omega^2 \delta_{ab}$ , are:

$$q^a = \Omega^{-1}(1, i), \quad q_a = \Omega(1, i),$$

### *Transformed variables*

We transform to the stereographic coordinates the variables:

$$(\gamma_{ij}, \hat{K}_{ij}, \hat{\mathbf{K}}_{ij}), \quad (\hat{N}^i, \mathbf{k}_i), \quad (\hat{N}, \hat{K}, \mathbf{K}, \kappa_0, \kappa)$$

# Projection

## Calculation of the stereographic projections

- Metric terms

$$a = \frac{1}{2} q^i \bar{q}^j \gamma_{ij}, \quad b = \frac{1}{2} q^i q^j \gamma_{ij}, \quad d = a^2 - b\bar{b},$$
$$A = d^{-1} [a(2\bar{\partial}a - \bar{\partial}b) - \bar{b}\bar{\partial}b], \quad B = d^{-1} [a\bar{\partial}b - b\bar{\partial}\bar{b}]$$
$$C = d^{-1} [a\bar{\partial}b - b(2\bar{\partial}a - \bar{\partial}b)], \quad \tilde{N} = q_i \hat{N}^i.$$

- Given terms

$$\hat{K} = q^i \bar{q}^j \hat{K}_{ij}, \quad \check{K} = q^i q^j \hat{K}_{ij}, \quad \dot{K} = q^i \bar{q}^j \check{K}_{ij}, \quad \ddot{K} = q^i q^j \check{K}_{ij}.$$

- Updated terms

$$U = \mathbf{K}, \quad v = q^i \mathbf{k}_i, \quad w = \kappa.$$

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# Algorithm

## Algebra

- 1 Module for calculating  $(h^{ij}, {}^3R, K_{ij}, K_i^i)$ .
- 2 Module for calculating  $(\hat{N}, \hat{N}^i, \gamma^{ij}, \hat{K}_{ij}, \hat{K}, \hat{K}_{ij}, \kappa_0)$  and  $\mathbf{k}_i, \mathbf{K}, \kappa$ .
- 3 Module for transformation to stereographic coordinates

## Integration

- 1 Module for the stereographic projections and source terms
- 2 Module for updating the evolution and algebraic equations

## Analysis

- 1 Module for implementing exact and perturbative test cases
- 2 Module for calculating errors and convergence rates

# Numerics

## Numerical Integration: Runge-Kutta 2<sup>nd</sup> and 4<sup>th</sup> Order

- Flexible, can start and stop at any given radius
- Allows update of the algebraic equation inside the integrator
- Incorporates internally two types of CFL conditions given by:
  - ① Constant (linear) radial grid step  $h \propto dqdp$
  - ② Variable (logarithmic) radial grid step  $h \propto rhodqdp$

## Radial dissipation and stereographic interpolation

$$\partial_\rho \rightarrow \partial_\rho + \epsilon \bar{\partial} \bar{\partial}^2, \text{ and } \partial_\rho \rightarrow \partial_\rho - \epsilon^4 \bar{\partial}^2 \bar{\partial}^2.$$

## Spatial Derivatives: Finite-Difference 2<sup>nd</sup> and 4<sup>th</sup> Order

- Radial derivatives:  $\partial_k \rightarrow \Delta_k + \mathcal{O}(\frac{h^n}{\sqrt{3}})$ ,  $\partial_\rho \rightarrow \partial_\rho x^k \partial_k$
- Angular derivatives:  $\bar{\partial}$  module previously implemented.



## Kerr-Schild Metric

The metric is given on the form:  $g_{ab} = \eta_{ab} + 2Hl_a l_b$ ,  $H = \frac{M}{r}$

- 1 Exact Schwarzschild in centered cartesian coordinates

$$(t, x^i), l_a = (1, \frac{x_i}{r}), r = \rho = \sqrt{\delta_{ij} x^i x^j}$$

- 2 Exact Schwarzschild in shifted cartesian coordinates

$$(t, \tilde{x} = x - x_0, \tilde{y} = y - y_0, z), l_a = (1, \frac{\tilde{x}_i}{r}), r = \sqrt{\delta_{ij} \tilde{x}^i \tilde{x}^j}$$

- 3 Boosted Schwarzschild in centered cartesian coordinates

$$(\tilde{t} = \gamma(t - vx), \tilde{x} = \gamma(x - vt), y, z), r = \sqrt{\delta_{ij} \tilde{x}^i \tilde{x}^j}, l_a = \Gamma_a^b \tilde{l}_b,$$

- 4 Perturbed Schwarzschild in centered cartesian coordinates

$$K_i^j \rightarrow K_i^j (1 + \frac{Y_{20}}{100})$$

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# Timeline

## Most of the code is already implemented

The radial foliation, the separation of variables, the stereographic projection, the source terms, the 2<sup>nd</sup> order integrator.

## The code passed two tests

The centered and perturbed Schwarzschild tests prove a clean second order convergence, and long time stability.

## Work in progress

- Test the code with the shifted and the boosted Schwarzschild
- Implement and test the 4<sup>th</sup> order radial integration
- Improve the angular derivative (Fourier or spherical harmonics)
- Implement and test  ${}^3R, K_{ij}, K_i^i, \widehat{K}_{ij}, \widehat{K}$